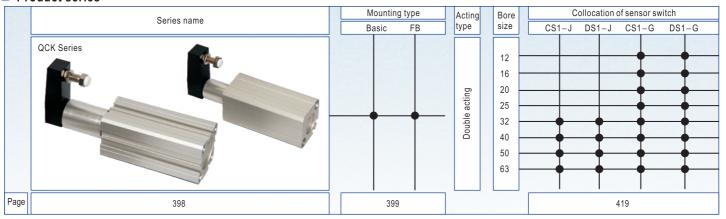


Rotary clamp cylinder——QCK Series

Product series



Installation and application



- 1. Dirty substances in the pipe must be eliminated before cylinder is connected with pipeline to prevent the entrance of impurities into the cylinder.
- 2. The medium used by cylinder shall be filtered to 40 μ m or below.
- 3. Anti-freezing measure shall be adopted under low temperature environment to prevent moisture
- 4. If the cylinder is dismantled and stored for a long time, please conduct anti-rust treatment to the surface. Anti-dust jam cap shall be added in air inlet and outlet ports.
- 5. To insure the life-span of cylinder and jig, please use flow control valve to control the speed of cylinder.

Criteria for selection: Cylinder thrust

Unit: Newton(N)

Bore size Rod size		A - 41 4	Operating pressure(MPa)										
(mm)	(mm)	Acting type	0.1	0.2	0.3	0.4	0.5	0.6	0.7	8.0			
40	_	IN(Clamp)	8.5	17.0	25.4	33.9	42.4	50.9	59.4	67.9			
12	6	OUT(Release)	11.3	22.6	33.9	45.2	56.5	67.9	79.2	90.4			
4.0	0	IN(Clamp)	15.1	30.2	45.2	60.3	75.4	90.5	105.6	120.6			
16	8	OUT(Release)	20.1	40.2	60.3	80.4	100.5	120.6	140.7	160.8			
00	40	IN(Clamp)	20.1	40.2	60.3	80.4	100.5	120.6	140.7	160.8			
20	12	OUT(Release)	31.4	62.8	94.2	125.7	157.1	188.5	219.9	251.3			
0.5	40	IN(Clamp)	37.8	75.6	113.3	151.1	188.9	226.7	264.4	302.2			
25	12	OUT(Release)	49.1	98.2	147.3	196.3	245.4	294.5	343.6	392.7			
00	4.0	IN(Clamp)	60.3	120.6	181.0	241.3	301.6	361.9	422.2	482.5			
32	16	OUT(Release)	80.4	160.8	241.3	321.7	402.1	482.5	563.0	643.4			
40	4.0	IN(Clamp)	105.6	211.1	316.7	422.2	527.8	633.3	738.9	844.5			
40	16	OUT(Release)	125.7	251.3	377.0	502.7	628.3	754.0	879.6	1005.3			
	00	IN(Clamp)	164.9	329.9	494.8	659.7	824.7	989.6	1154.5	1319.5			
50	20	OUT(Release)	196.3	392.7	589.0	785.4	981.7	1178.1	1374.4	1570.8			
00	20	IN(Clamp)	280.3	560.6	840.9	1121.2	1401.5	1681.9	1962.2	2242.5			
63 20	OUT(Release)	311.7	623.4	935.2	1246.9	1558.6	1870.3	2182.1	2493.8				



Rotary clamp cylinder

QCK Series



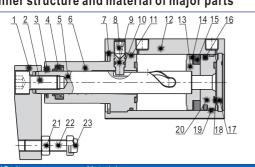
Symbol



Product feature

- 1. It can be used on welding fixfure, the QPQ surface treatment prevent piston rod damage by welding slag; better than chrome plated piston rod.
- 2. The front cover with stainless steel dust scraping ring, can keep the dust and welding slag out, and protect cylinder internal parts.
- 3. Strong magnet is optioned for $\,\Phi\,32\sim\,\Phi\,63$ bore size , which can be used in high magnetic fields.
- 4. The mounting dimension of body is the same as ACQ series, can use ACQ $\,$

Inner structure and material of major parts



1	Rocker	Carbon steel
2	Screw	Carbon steel
3	Dust scraping ring	No(Φ12, Φ16)\Stainless steel(Others)
4	Front cover packing	NBR
5	Piston rod	SCr440
6	Front cover	Aluminum alloy
7	C Clip	Spring steel
8	Screw	Carbon steel
9	Operating screw	SCr440
10	O-ring	NBR
11	O-ring	NBR
12	Body	Aluminum alloy
13	Magnet holder	Brass(Φ 12, Φ 16)\Aluminum alloy(Others)
14	Magnet washer	NBR
15	Magnet	Sintered metal(Neodymium-iron-boron(Ф 12~ Ф 25)
		Plastic(Others)
16	Piston seal	NBR
17	Back cover	Aluminum alloy
18	Bumper	TPU(Φ 12~ Φ 25)\NBR(Others)
19	Wear ring	No(Ф 12~ Ф 32)\Wear resistant material(Others)
20	Piston	Brass(Φ 12, Φ 16)\Aluminum alloy(Others)
21	Screw	Carbon steel
22	Fixing screw	Carbon steel
23	Bumper	PTFE(Ф 12~ Ф 40)\POM(Others)

Specification

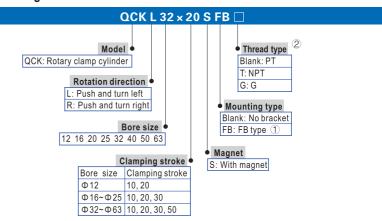
Bore size(mm)	12	16	20	25	32	40	50	63			
Acting type		Double acting									
Fluid		Air(to be filtered by 40 μ m filter element)									
Operating pressure			0.15~	1.0MPa(23	~145psi)(1.5	5~10bar)					
Proof pressure		1.5MPa(215psi)(15bar)									
Temperature °C		-20~80									
Speed range mm/s		50~200									
Rotation angle				90°	± 10°						
Rotation direction				Turn left	or turn right						
Rotation stroke mm		7.5	(9.5		15		19			
Clamping stroke mm	10 20		10 20 30		10 20 30 50						
Stroke tolerance		+1.0 0									
Cushion type	Bumper										
Port size ①		M5 × 0.8 1/8" 1/									

AITTAC

1) PT thread, NPT and G thread are available.

 $Add)\ QCK\ series\ are\ all\ attached\ with\ magnet,\ please\ refer\ to\ Page\ 419\sim442\ for\ the\ specific\ content\ of\ sensor\ switch.$

Ordering code

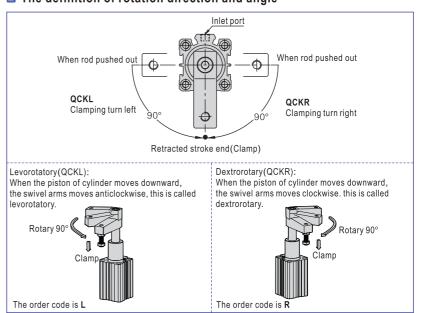


① Back flange is same as ACQ series (please refer below table), if need front flange, please contact us.

Bore size\Accessories	FB	Material	Bore size\Accessories	FB	Material		
12	F-ACQ12FA	Aluminum allov	32	F-ACQ32FA			
16	F-ACQ16FA	Aluminum alloy	40	F-ACQ40FA	Croy cost iron		
20	F-ACQ20FA	Crow cost iron	50	F-ACQ50FA	Grey cast iron		
25	F-ACQ25FA	Grey cast iron	63	F-ACQ63FA			

2 When the thread is standard, the code is blank.

The definition of rotation direction and angle

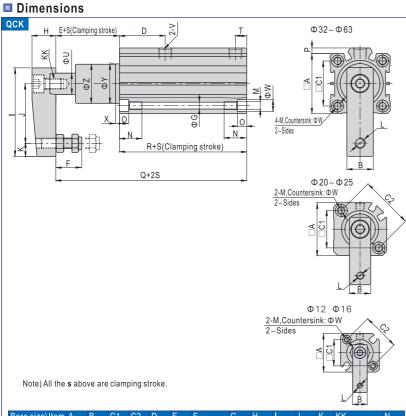






Rotary clamp cylinder

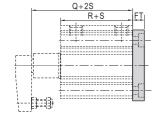
QCK Series

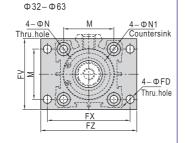


Bore size\Item	Α	В	C1	C2	D	Е	F	G	Н			K	KK	N
12	25	9	15.5	22	13.5	10.5	7~13	3.4	9	29	20	4	$M3 \times 0.5$	11
16	29	11	20	28	15	10.5	7~13	3.4	13	36	25	5	$M5 \times 0.8$	11
20	36	16	25.5	36	30	8	9.5~20.5	5.2	16	51	35	7	M8 × 1.25	17
25	40	16	28	40	30	8	9.5~20.5	5.2	16	51	35	7	M8 × 1.25	17
32	45	19	34	-	34.5	17.5	13.5~25.5	5.2	19	67	45	10	$M10 \times 1.5$	17
40	53	19	40	-	26.5	25	13.5~25.5	5.2	19	67	45	10	$M10 \times 1.5$	17
50	64	25.4	50	-	34	31	14.5~30	6.5	25.4	88	65	10	$M12 \times 1.75$	22
63	77	25.4	60	-	34.5	30.5	14.5~30	8.7	25.4	88	65	10	$M12 \times 1.75$	28.5
								-				147		_

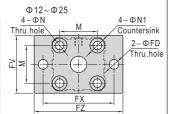
Bore size\Item	L	M	0	Р	Q	R	Т	U		W	Χ		Z
12	$M4 \times 0.7$	$M4 \times 0.7$	3.5	-	46	35.5	5.5	6	$M5 \times 0.8$	6.5	3	11	10.8
16	$M4 \times 0.7$	$M4 \times 0.7$	3.5	-	46	35.5	5.5	8	$M5 \times 0.8$	6.5	3	14	13.8
20	$M6 \times 1.0$	$M6 \times 1.0$	7	-	70	62	6	12	$M5 \times 0.8$	9	3	18	17.8
25	$M6 \times 1.0$	$M6 \times 1.0$	7	-	71	63	7	12	$M5 \times 0.8$	9	6	23	22.5
32	$M8 \times 1.25$	$M6 \times 1.0$	7	4.5	89	71.5	8.5	16	1/8"	9	7	30	29.5
40	$M8 \times 1.25$	M6 × 1.0	7	4	90	65	9	16	1/8"	9	3	30	29.5
50	$M10 \times 1.5$	M8 × 1.25	8	7	107.5	76.5	11.5	20	1/4"	11	3.5	37	36.5
63	$M10 \times 1.5$	$M10 \times 1.5$	10.5	7	110.5	80	11.5	20	1/4"	14	3.5	48	47.5

QCK-FB



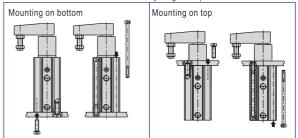


Bore size\Item	R	Q	М	N	N1	FD	FT	F۷	FX	FZ
12	35.5	46	15.5	4.5	7.5	4.5	5.5	25	45	55
16	35.5	46	20	4.5	7.5	4.5	5.5	30	45	55
20	62	70	25.5	6.5	10.5	6.5	8	39	48	60
25	63	71	28	6.5	10.5	6.5	8	42	52	64
32	71.5	89	34	6.5	10.5	5.5	8	48	56	65
40	65	90	40	6.5	10.5	5.5	8	54	62	72
50	76.5	107.5	50	8.5	13.5	6.5	9	67	76	89
63	80	110.5	60	10.5	16.5	9	9	80	92	108

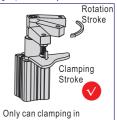


Installation and operation

- 1. To insure the life-span of cylinder and jig, please use flow control valve to control the speed of cylinder.
- 2. The method of installation are mounted by flange on top or bottom.

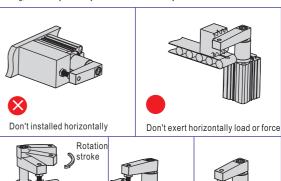


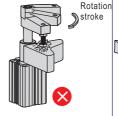
- ${\it 3. Befor the cylinder is connected to pipeline sundries in the pipe must be eliminated,}\\$ or may cause leakage.
- 4. Please clean the piston-rod and dust scraping ring to protect the cylinder
- 5. The cylinder using normal magnet ring can use the same sensor as ACQ series. For the cylinder using strong magnet ring we suggest using AirTAC's CS1-69AM sensor.
- 6. Because the rotary force is strong when the cylinder's acting, we suggest using flow control valve to control the speed to protect cylinder.
- 7. Please install the cylinder following the right diagram.
- 8. The installation method as the diagram below is wrong, and will injure the cylinder and shorten the cylinder life.



AITTAC









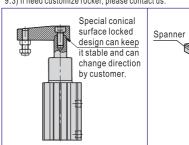


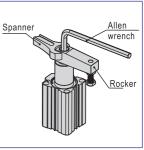
workpiece when clamped

Please don't clamp

when rotating

- 9.1) The design of rocker can keep it stable and can change direction by customer.
- 9.2) Please follow the diagram below on right side to assemble/disassemble the rocker by spanner and allen wrench; don't hold the body to assemble/disassemble rocker, or will damage the cylinder.
- 9.3) If need customize rocker, please contact us.







QCK

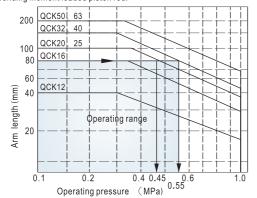
Jig mass :m2

QCK Series

How to select product

- 1. When arms are to be made separately, their length and weight should be within the following range.
- 2. Allowable bending moment:

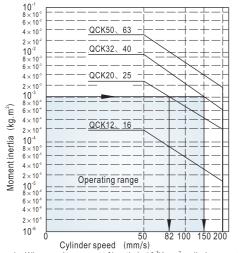
Use the arm length and operating pressure within graph(1) for allowable bending moment loaded piston rod.



Example: When arm length is 80mm, pressure should be less than QCK20/25:0.45MPa QCK32/40:0.55MPa

3. Moment of inertia:

When the arm is long and heavy, damage of internal parts may be caused due to inertia. Use the inertia moment and cylinder speed within graph(2) based on arm requirments.



Example: When arm's moment of inertia is 10^{-3} Kg·m², cylinder speed should

be less than

QCK20/25:82mm/s

Note) The average speed of piston=the highest speed of piston/1.6

4. Moment of inertia of cylinder's arm when rotating based on its rotary axis. shown in graph(3).

Model	Moment of inertia (Kg·m²)
QCK12	3.555×10^{-6}
QCK16	1.053×10^{-5}
	5.257×10^{-5}
QCK32\40	1.653×10^{-4}
QCK50\63	7.387×10^{-4}

- 5. Calculation reference:
 - 5.1 Moment of inertia of arm (I1): Refer to the graph(3) after the cylinder bore diameter is determined.
 - 5.2 Moment of inertia of jig (I2): According to shape of the jig and the next item 6 "Calculation for moment of inertia", pick out a proper formula for calculation. The jig shown on the right graph is a cylinder ,its formula of moment of inertia is:

 $I_2 = (m_2 * D * D)/8 + m_2 * L * L$

When QCK32 is selected: L=0.045m(arm length);

If D=0.04m $m_2 = 0.4 kg$ From graph(3): $I_1 = 1.653 \times 10^{-4} (\text{Kg} \cdot \text{m}^2)$

By Calculation : $I_2 = (m_2 * D * D)/8 + m_2 * L * L = (0.4 * 0.04 * 0.04)/8 + 0.4 * 0.045 *$

 $=8.9\times10^{-4}(\text{Kg}\cdot\text{m}^2)$

Total value: $I = I_1 + I_2 = 10.553 \times 10^{-4} = 1.0553 \times 10^{-3} (\text{Kg} \cdot \text{m}^2)$

 $According \ to \ graph (2), the \ highest \ speed \ of \ the \ cylinder \ should \ be \ less \ than \ 150 \ mm/s; \ According \ to$ $graph(1), it\ can\ be\ used\ under\ a\ pressure\ of\ 0.9 Mpa.\ The\ average\ speed\ of\ piston=the\ highest\ speed$ of piston/1.6=94 mm/s.

Calculation for moment of inertia	
Diagram	Calculation formula of moment of inertia
1. Thin bar Position of rotary axis: Vertical to the bar and through the end	$I = \frac{m_1 a_1^2 + m_2 a_2^2}{3}$
2. Thin bar Position of rotary axis: Vertical to the bar and through the center of gravity	$I = \frac{ma^2}{12}$
3. Load at the end of lever arm a ₂ m ₁ m ₂	$I = m_{1} \times \frac{a_{1}^{2}}{3} + m_{2} \times a_{2}^{2} + k$ $k = m_{2} \times \frac{2r^{2}}{5}$
4. Thin rectangular plate (Rectangular parallelepiped) Position of rotary axis:Parallel to side b and through the center of gravity	$I = \frac{ma^2}{12}$
5. Thin rectangular plate (Rectangular parallelepiped) Position of rotary axis: Vertica to the plate and through the end	$I=m_{1}\times \frac{4a_{1}^{2}+b^{2}}{12}+m_{2}\times \frac{4a_{2}^{2}+b^{2}}{12}$
6. Thin rectangular plate (Rectangular parallelepiped) Position of rotary axis:Through the center of gravity and vertical to the plate(Same as also thickrectanglaur plate)	$I = \frac{ma^2 + mb^2}{12}$